

Efficient Computation of Reverse Skyline Queries

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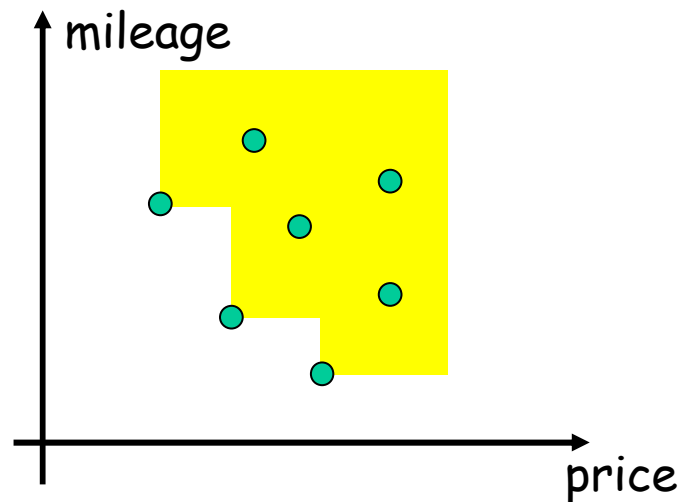
Bernhard Seeger (University of Marburg, Germany)

Outline

- Skyline
- Dynamic Skyline Query
- Reversed Skyline Query
- Branch-and-Bound for Reversed Skylines
- Reversed Skylines with Approximations
- Experimental Results

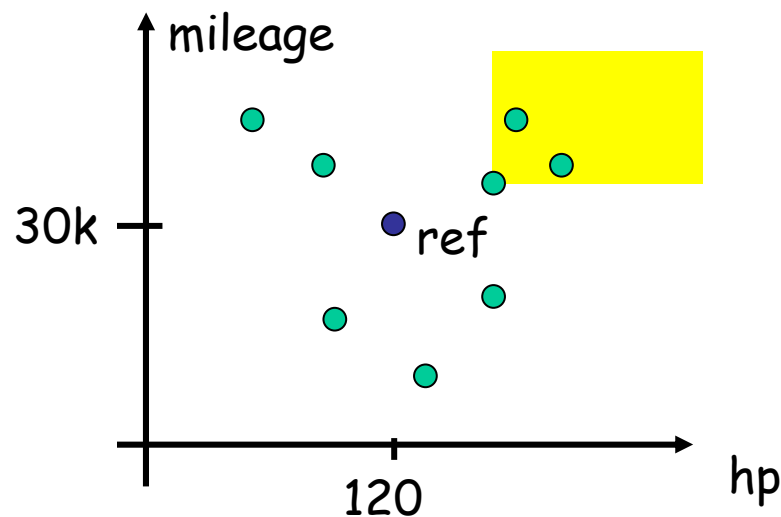
Skyline

- Important new class of queries
 - Given: a set of **d-dimensional** points
 - Result: points that are not dominated by others
 - x dominates y
 x is as good as y in all dimensions and better in at least one dimension
- Example (collection of used cars)
 - Goal: Cheapest car with lowest mileage



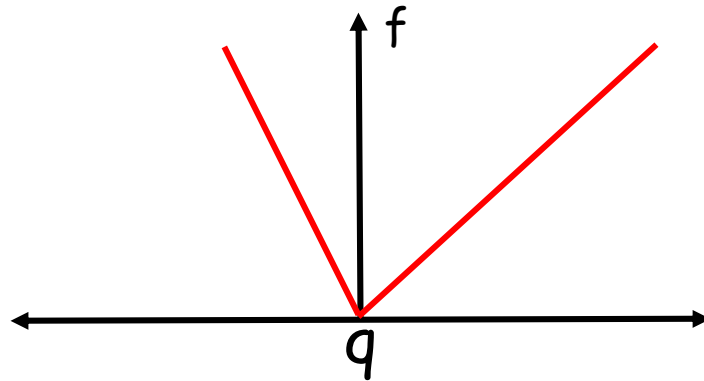
2. Dynamic Skyline Query

- Motivation (customer perspective)
 - ideal used car: 120 hp, 30000 km, build 2005, ...
 - Find all cars that are close to customer's specification
- Skyline query relative to a **reference point ref**
 - x dominates y iff x is not farther from ref than y in all dimensions and in at least one dimension closer to ref
- Example (Used Car Database)



The distance function

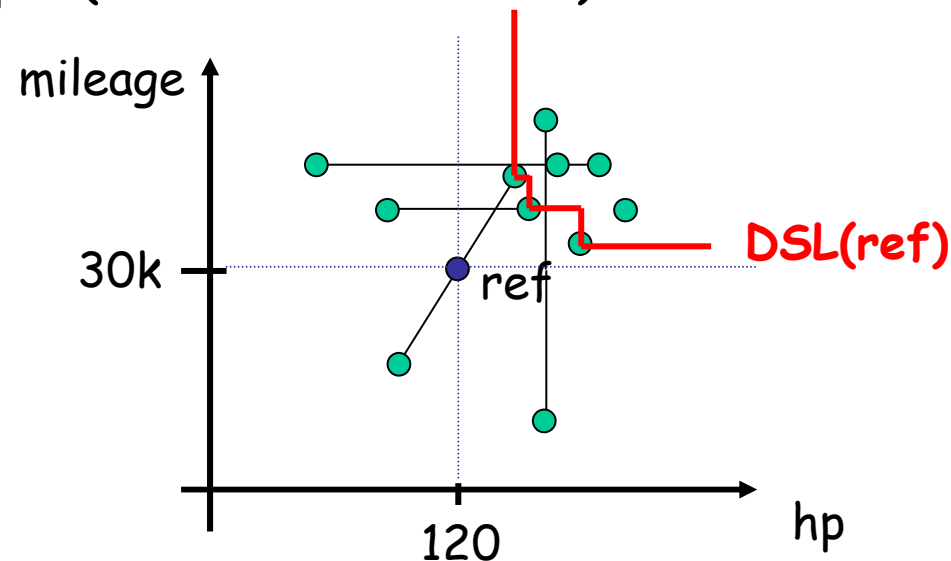
- Distance function $f: \mathbb{R}^d \rightarrow \mathbb{R}^d$
 - $f(q) = (0, \dots, 0)$
 - $f(c_1, \dots, c_{i-1}, x_i, c_{i+1}, \dots, c_d)$ linear decreasing in x_i , $x_i < q_i$
 - $f(c_1, \dots, c_{i-1}, x_i, c_{i+1}, \dots, c_d)$ linear increasing in x_i , $x_i > q_i$



- Generalization to a more general class is possible
- Without loss of generality
 $f(x) = (|x_1 - q_1|, |x_2 - q_2|, \dots, |x_d - q_d|)$

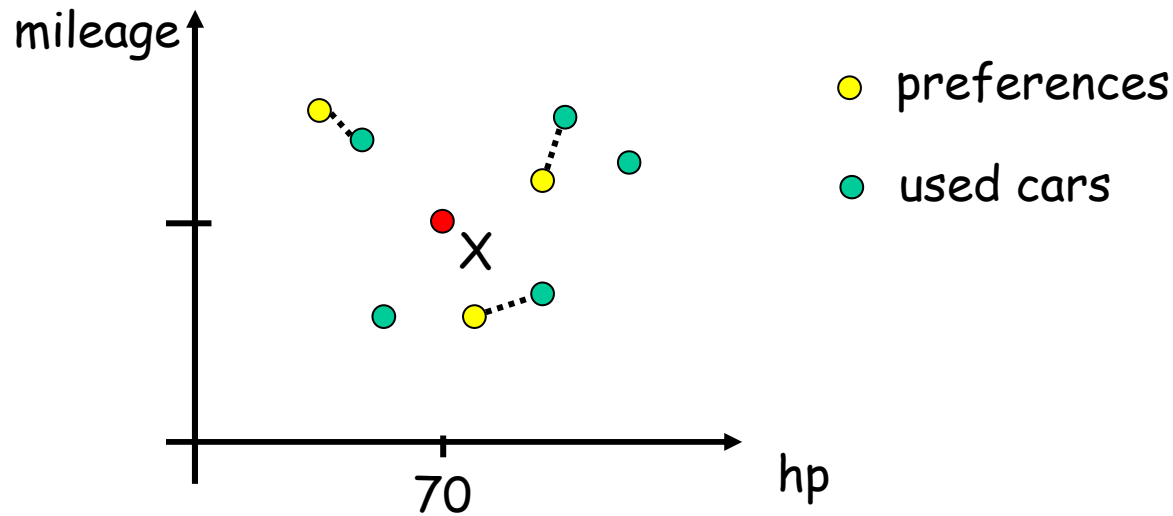
Dynamic Skyline Query

- Motivation (customer perspective)
 - ideal used car: 120 hp, 30000 km, build 2005, ...
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3. Reverse Skyline Query

- Motivation (dealer perspective)
 - Given: the preferences of customers, the collection of used cars
 - Does it make sense to offer a car X to one of my customers?
Car X is interesting, if it is in the skyline of a preference.

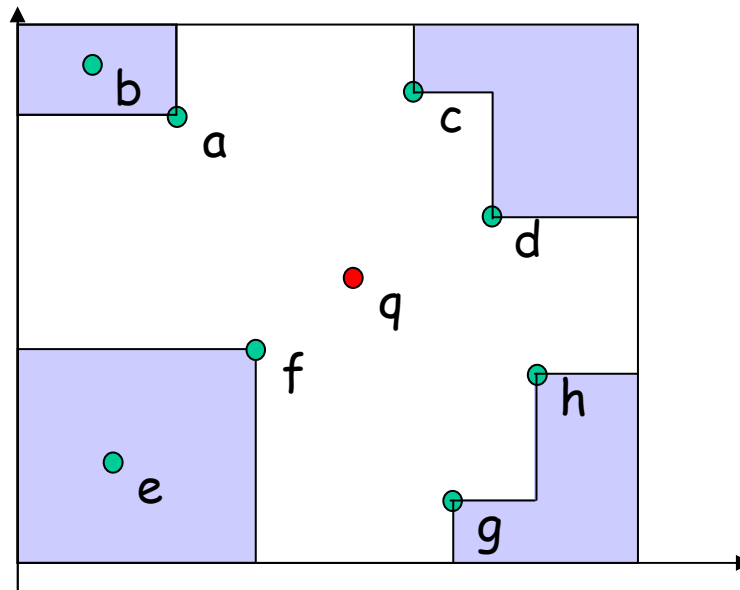


Reverse Skyline Query

- Monochromatic Problem
 - Given a set P of d -dimensional points and a query point q
- Reverse Skyline query of q
 - $RSL(q)$ = points whose skyline contains q
- Two Algorithms
 - Assumption: R-tree on set P
 - Branch-and-bound algorithm (BBRS)
 - Reversed Skyline Search with Approximations (RSSA)

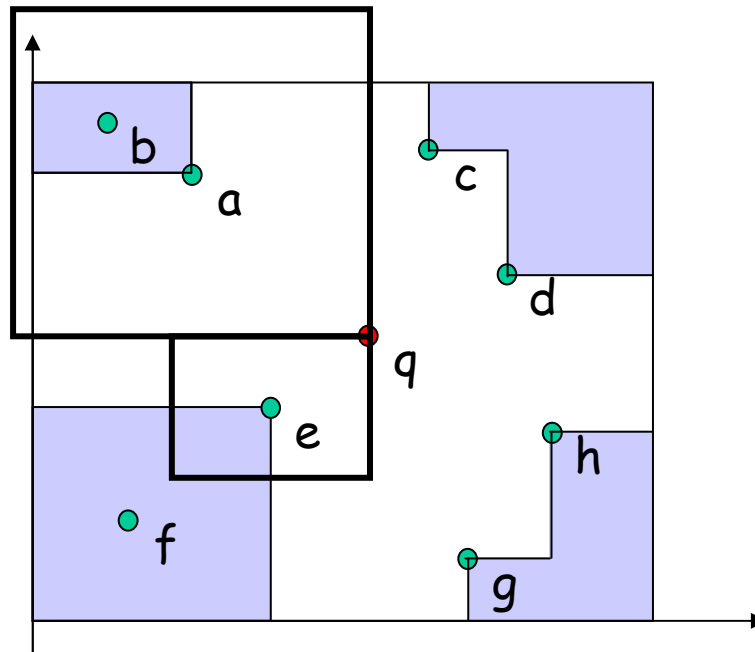
4. BBRs: Branch-and-Bound algorithm

- Assumption
 - Multidimensional index (e.g. R-tree) on point set P
- Goal
 - Processing reversed skyline of point q without transformation
- Global Skyline $GSL(q)$
 - points that are not globally dominated
 - **point x globally dominates y ,**
if ε in $\{-1, 1\}^d$ exists such that for all i : $0 \leq \varepsilon_i (x_i - q_i) \leq \varepsilon_i (y_i - q_i)$



Important Properties

- $RSL(q) \subseteq GSL(q)$
- A point $a \in GSL(q)$ is not in $RSL(q)$ if there is a $b \in P$ such that for all i : $|b_i - a_i| < |a_i - q_i|$.



Algorithm BBRS

- Given: query point q , point set P
- Return the reversed skyline $RSL(q)$

Sketch

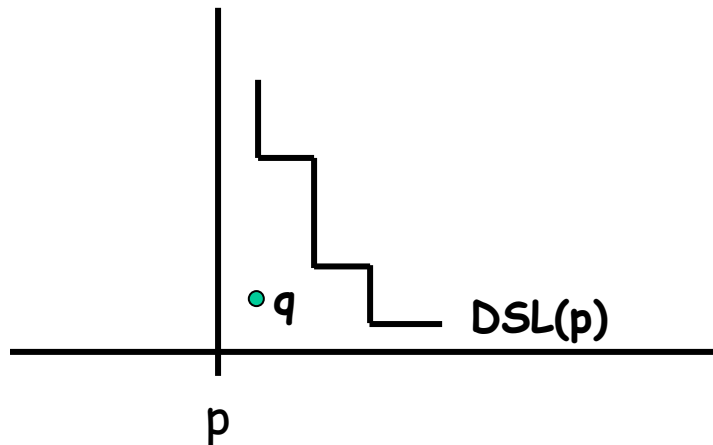
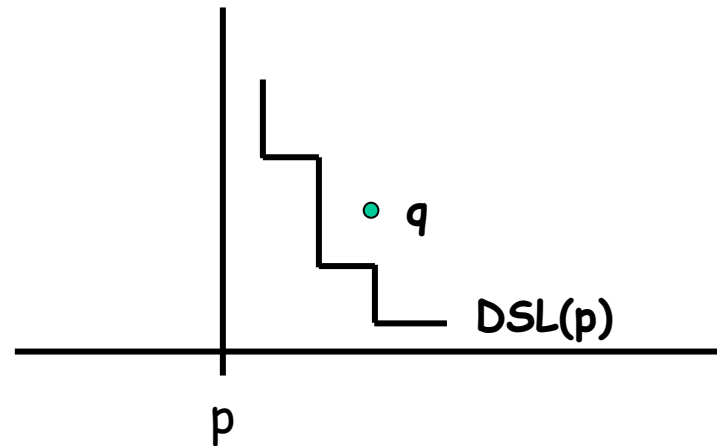
- **Candidate generation:**
branch-and-bound computation of the global skyline $GSL(q)$
- For each candidate p in $GSL(q)$ perform a **boolean window query**

Results

- **Correctness**
- **Minimum number of candidates**

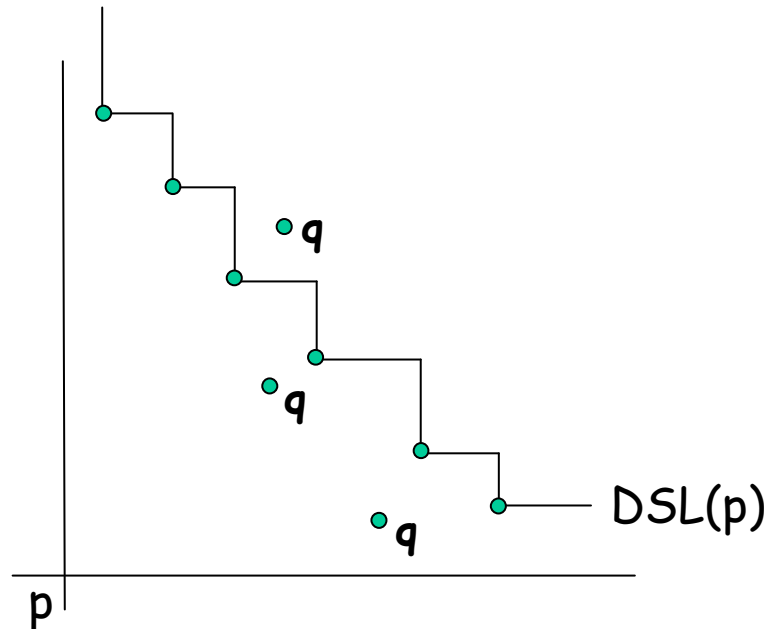
5. Reverse Skyline with Approximations

- Important property
If any s from $DSL(p)$ dominates $q \iff p$ is not in $RSL(q)$



Approximations

- For each p we keep a subset of $DSL(p)$ of constant size
 - Parameter k

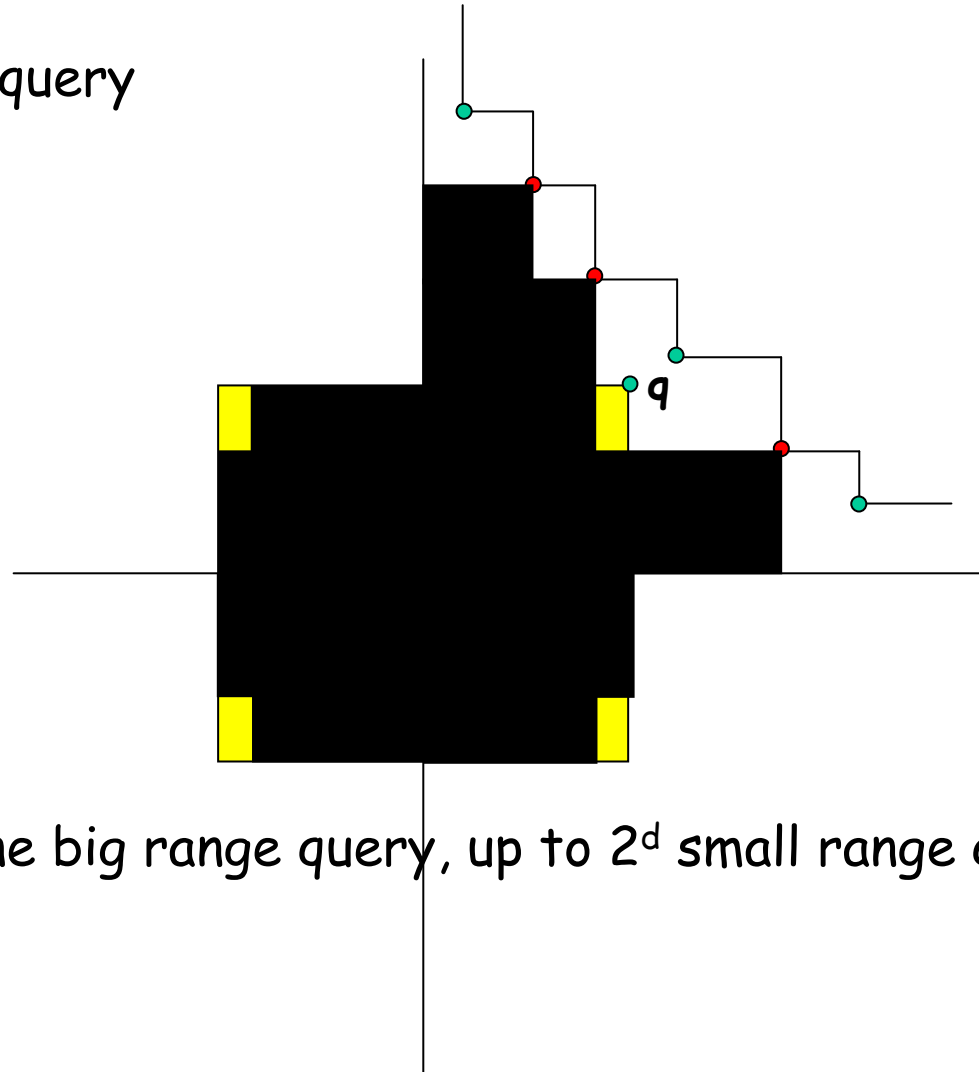


- Filter Step
 - If q dominates one of the samples $\rightarrow p$ is in $RSL(q)$
 - If a sample dominates $q \rightarrow p$ is not in $RSL(q)$
 - Otherwise, call the refinement step



Refinement Step

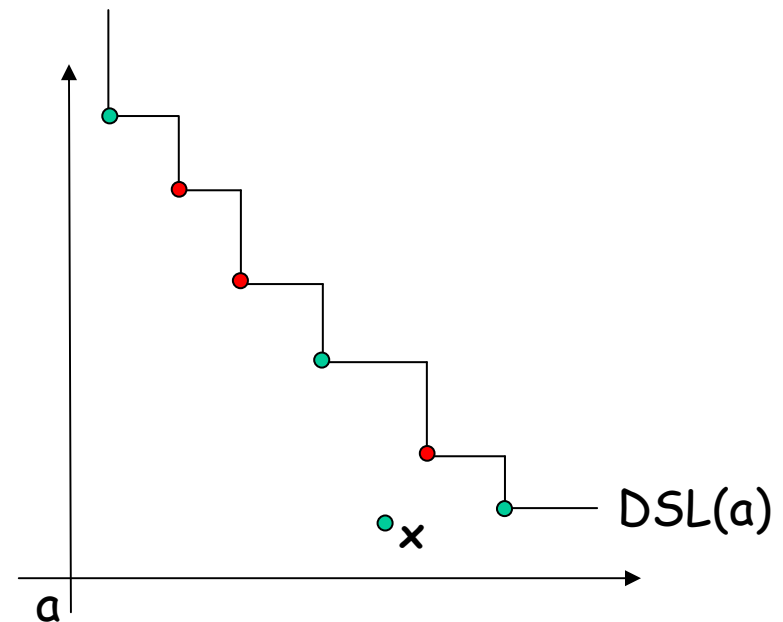
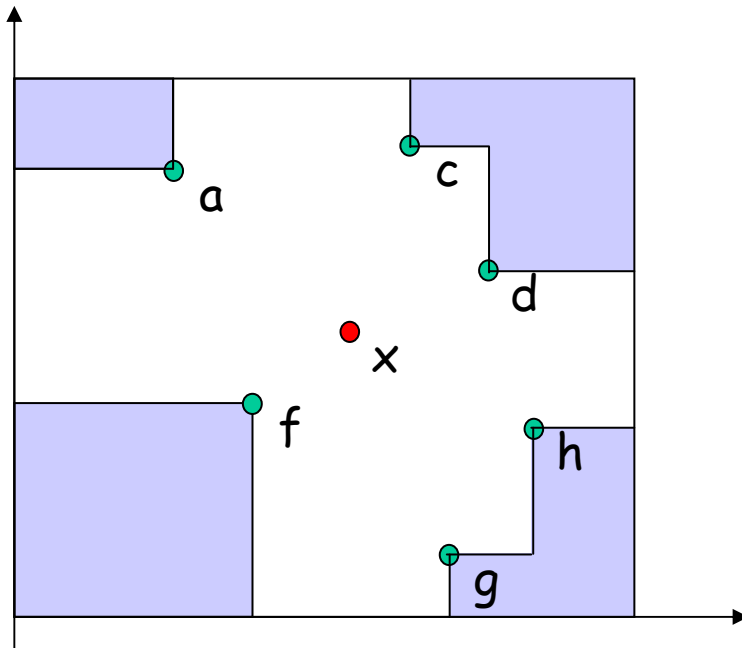
- Empty range query



- Instead of one big range query, up to 2^d small range queries

Dynamic Maintenance

- Insertion of a new point x
- Algorithm
 - Compute the global skyline $GSL(x)$
 - For every $a \in GSL(x)$ examine the approximation of $DSL(p)$.
If x dominates at least one sample \rightarrow Update the approximation



Computing Approximations

- $d=2$
 - An algorithm based on the dynamic programming paradigm produces an optimal approximation.
- $d>2$
 - Greedy-algorithm
Iteratively add the point with the maximum approximation gain

Related literature

- Jagadish et al.: Optimal Histograms with Quality Guarantees, VLDB 1998
- Xuemin Lin, Yidong Yuan, Qing Zhang, Ying Zhang : Selecting Stars: The k Most Representative Skyline Operator, ICDE 2007

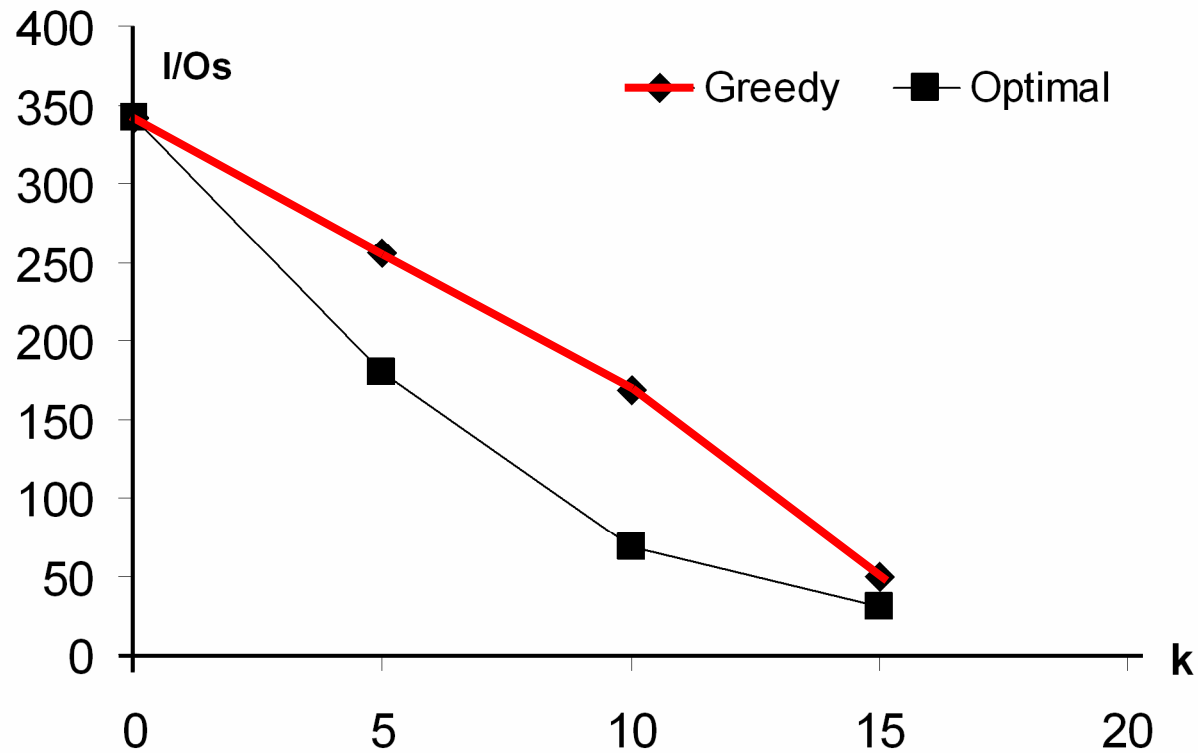
6. Experiments

- Data sets
 - Real Data
 - CarDB: $d = 2$; $N = 50000$
 - NBA: $d = 4$; $N = 17000$
 - Synthetic Data
 - Uniform distribution: $d=2,\dots,4$; $N = 80000$
 - Cluster distribution: $d = 2,\dots,4$; $N = 80000$
- Queries
 - 100 reversed skyline queries
- Implementation
 - XXL library (newest version on request)



RSSA algorithm

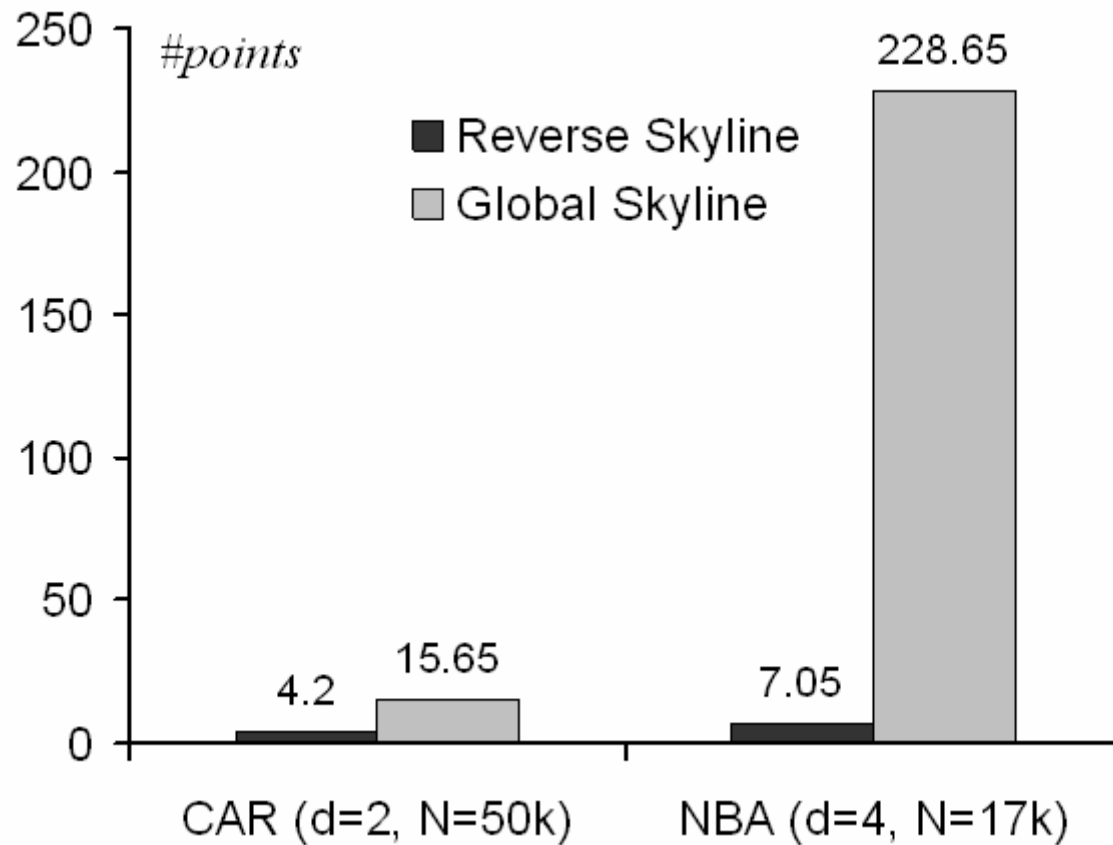
- Performance as a function of k





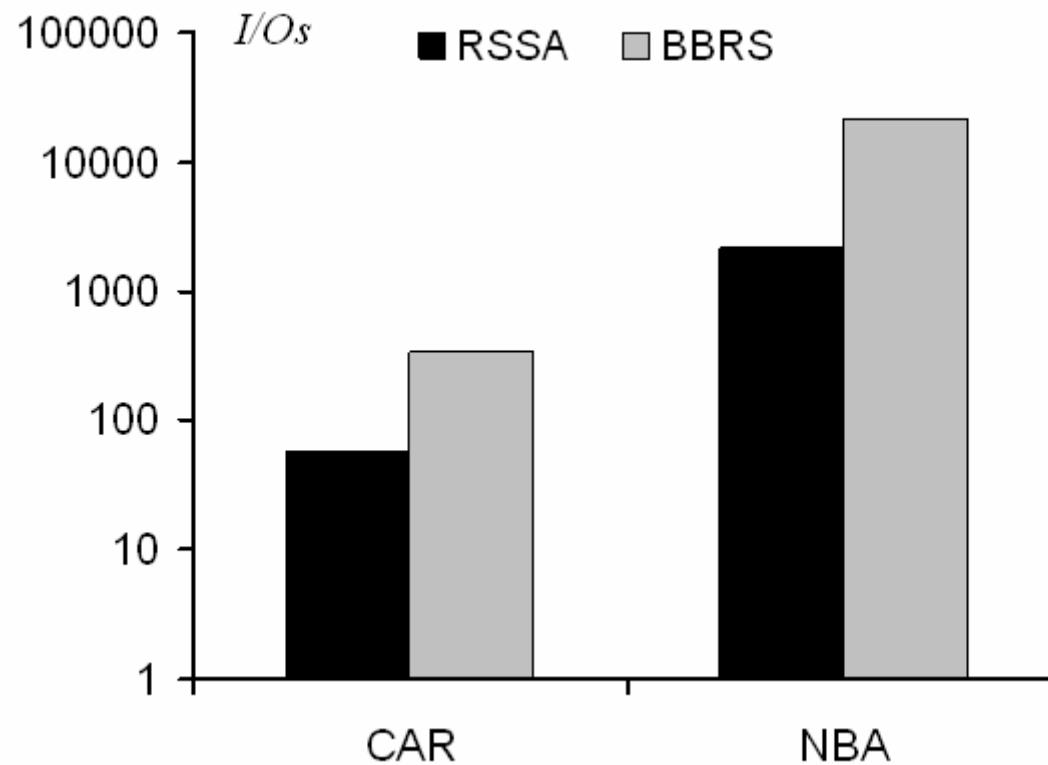
Size of the reversed skyline

- in comparison to the size of the global skyline



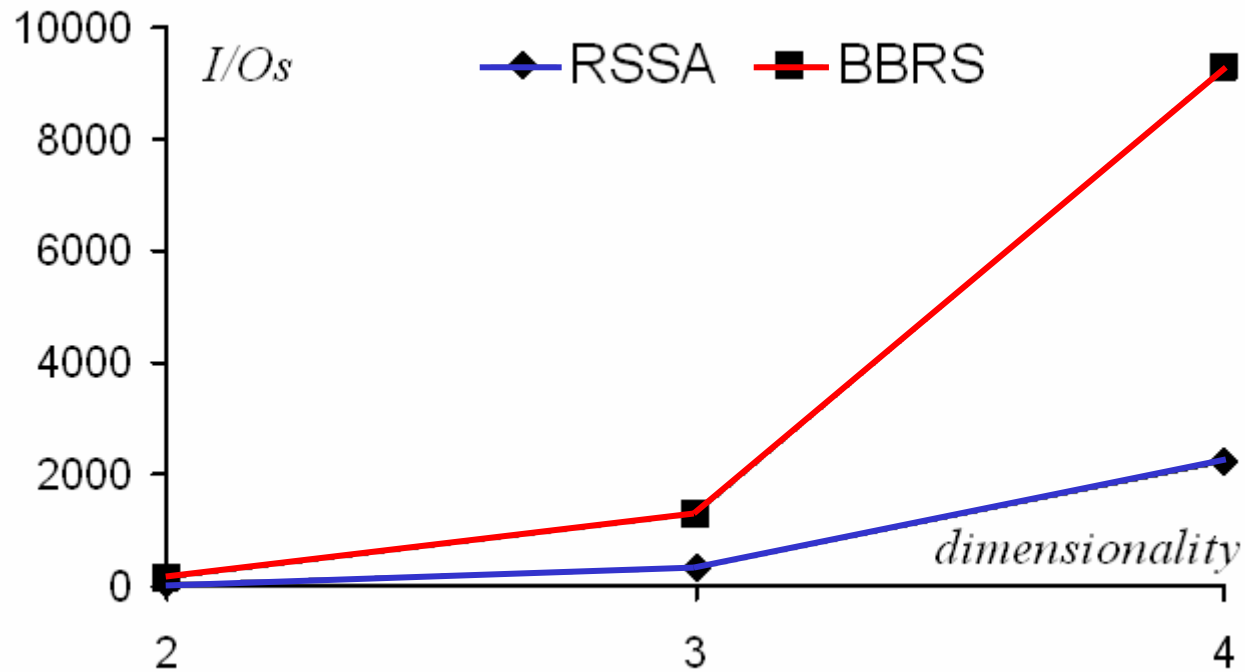
Comparison RSSA vs. BBRs

- Average number of I/Os (logarithmic scale)



Comparison RSSA vs. BBRS

- Performance as a function of dimensionality



- Reverse Skylines are important for finding interesting points
 - Dealer perspective:
What kind of items are interesting to my customers?
- Two Algorithms
 - BBR5
 - Adaptation of the original BBS algorithm
 - RSSA
 - Filter-and-refinement paradigm
 - Preprocessing approximations of skylines
 - Updates are expensive
- Future Work
 - Accurate Approximation of skylines for $d > 2$
 - Bichromatic Reversed Skylines